

# **Mark Scheme 4727 June 2007**

<p><b>1 (i)</b> <math>z z^* = r e^{i\theta} \cdot r e^{-i\theta} = r^2 =  z ^2</math></p>	<p>B1 <b>1</b></p>	<p>For verifying result <b>AG</b></p>
<p><b>(ii)</b> Circle Centre <math>0 (+0i)</math> OR <math>(0, 0)</math> OR <math>O</math>, radius 3</p>	<p>B1 B1 <b>2</b> <b>3</b></p>	<p>For stating circle For stating correct centre and radius</p>
<p><b>2 EITHER:</b> <math>(\mathbf{r} \Rightarrow) [3+t, 1+4t, -2+2t]</math> <math>8(3+t) - 7(1+4t) + 10(-2+2t) = 7</math> <math>\Rightarrow (0t) + (-3) = 7 \Rightarrow</math> contradiction <math>l</math> is parallel to <math>\Pi</math>, no intersection</p>	<p>M1 M1 A1 A1 B1 <b>5</b></p>	<p>For parametric form of <math>l</math> seen or implied For substituting into plane equation For obtaining a contradiction For conclusion from correct working</p>
<p>OR: <math>[1, 4, 2] \cdot [8, -7, 10] = 0</math> <math>\Rightarrow l</math> is parallel to <math>\Pi</math> <math>(3, 1, -2)</math> into <math>\Pi</math> <math>\Rightarrow 24 - 7 - 20 \neq 7</math> <math>l</math> is parallel to <math>\Pi</math>, no intersection</p>	<p>M1 A1 M1 A1 B1</p>	<p>For finding scalar product of direction vectors For correct conclusion For substituting point into plane equation For obtaining a contradiction For conclusion from correct working</p>
<p>OR: Solve <math>\frac{x-3}{1} = \frac{y-1}{4} = \frac{z+2}{2}</math> and <math>8x - 7y + 10z = 7</math> eg <math>y - 2z = 3, 2y - 2 = 4z + 8</math>  eg <math>4z + 4 = 4z + 8</math> <math>l</math> is parallel to <math>\Pi</math>, no intersection</p>	<p>M1 A1 M1 A1 B1 <b>5</b></p>	<p>For eliminating one variable For eliminating another variable For obtaining a contradiction For conclusion from correct working</p>
<p><b>3</b> Aux. equation <math>m^2 - 6m + 8 (= 0)</math> <math>m = 2, 4</math> CF <math>(y \Rightarrow) A e^{2x} + B e^{4x}</math> PI <math>(y \Rightarrow) C e^{3x}</math> <math>9C - 18C + 8C = 1 \Rightarrow C = -1</math> GS <math>y = A e^{2x} + B e^{4x} - e^{3x}</math></p>	<p>M1 A1 A1√ M1 A1 B1√ <b>6</b> <b>6</b></p>	<p>For auxiliary equation seen For correct roots For correct CF. f.t. from their <math>m</math> For stating and substituting PI of correct form For correct value of <math>C</math> For GS. f.t. from their CF + PI with 2 arbitrary constants in CF and none in PI</p>

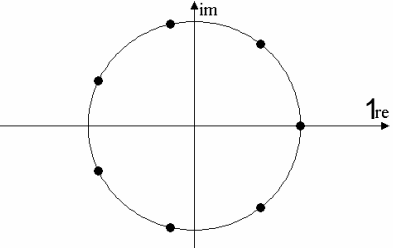
4727

Mark Scheme

June 2007

<p><b>4 (i)</b> <math>q(st) = qp = s</math> <math>(qs)t = tt = s</math></p>	<p>B1 B1 <b>2</b></p>	<p>For obtaining <math>s</math> For obtaining <math>s</math></p>
<p><b>(ii) METHOD 1</b> Closed: see table Identity = <math>r</math> Inverses: <math>p^{-1} = s, q^{-1} = t, (r^{-1} = r),</math> <math>s^{-1} = p, t^{-1} = q</math></p>	<p>B1 B1 M1 A1 <b>4</b></p>	<p>For stating closure with reason For stating identity <math>r</math> For checking for inverses For stating inverses <i>OR</i> For giving sufficient explanation to justify each element has an inverse eg <math>r</math> occurs once in each row and/or column</p>
<p><b>METHOD 2</b> Identity = <math>r</math>  eg <math>p^2 = t, p^3 = q, p^4 = s</math>  <math>\Rightarrow p^5 = r</math>, so <math>p</math> is a generator</p>	<p>B1 M1 A1 A1</p>	<p>For stating identity <math>r</math> For attempting to establish a generator <math>\neq r</math> For showing powers of <math>p</math> (<i>OR</i> <math>q, s</math> or <math>t</math>) are different elements of the set For concluding <math>p^5</math> (<i>OR</i> <math>q^5, s^5</math> or <math>t^5</math>) = <math>r</math></p>
<p><b>(iii)</b> <math>e, d, d^2, d^3, d^4</math></p>	<p>B2 <b>2</b> <b>8</b></p>	<p>For stating all elements <b>AEF</b> eg <math>d^{-1}, d^{-2}, dd</math></p>

<p><b>5 (i)</b> <math>(\cos 6\theta =) \operatorname{Re}(c + is)^6</math>  <math>(\cos 6\theta =) c^6 - 15c^4s^2 + 15c^2s^4 - s^6</math> <math>(\cos 6\theta =)</math> <math>c^6 - 15c^4(1 - c^2) + 15c^2(1 - c^2)^2 - (1 - c^2)^3</math> <math>(\cos 6\theta =) 32c^6 - 48c^4 + 18c^2 - 1</math></p>	<p>M1 A1 M1 A1 <b>4</b></p>	<p>For expanding (real part of) <math>(c + is)^6</math> at least 4 terms and 1 evaluated binomial coefficient needed For correct expansion For using <math>s^2 = 1 - c^2</math> For correct result <b>AG</b></p>
<p><b>(ii)</b> <math>64x^6 - 96x^4 + 36x^2 - 3 = 0 \Rightarrow \cos 6\theta = \frac{1}{2}</math>  <math>\Rightarrow (\theta =) \frac{1}{18}\pi, \frac{5}{18}\pi, \frac{7}{18}\pi</math> etc.  <math>\cos 6\theta = \frac{1}{2}</math> has multiple roots largest <math>x</math> requires smallest <math>\theta</math> <math>\Rightarrow</math> largest positive root is <math>\cos \frac{1}{18}\pi</math></p>	<p>M1 A1 M1 A1 <b>4</b>  <b>8</b></p>	<p>For obtaining a numerical value of <math>\cos 6\theta</math> For any correct solution of <math>\cos 6\theta = \frac{1}{2}</math> For stating or implying at least 2 values of <math>\theta</math> For identifying <math>\cos \frac{1}{18}\pi</math> <b>AEF</b> as the largest positive root from a list of 3 positive roots <i>OR</i> from general solution <i>OR</i> from consideration of the cosine function</p>

<p><b>6 (i)</b> <math>\mathbf{n} = l_1 \times l_2</math>  <math>\mathbf{n} = [2, -1, 1] \times [4, 3, 2]</math>  <math>\mathbf{n} = k[-1, 0, 2]</math>  <math>[3, 4, -1] \cdot k[-1, 0, 2] = -5k</math>  <math>\mathbf{r} \cdot [-1, 0, 2] = -5</math></p>	<p>B1 M1* A1 M1 (*dep) A1 <b>5</b></p>	<p>For stating or implying in (i) or (ii) that <math>\mathbf{n}</math> is perpendicular to <math>l_1</math> and <math>l_2</math>                  For finding vector product of direction vectors                  For correct vector (any <math>k</math>)                  For substituting a point of <math>l_1</math> into <math>\mathbf{r} \cdot \mathbf{n}</math>                  For obtaining correct <math>p</math>. <b>AEF</b> in this form</p>
<p><b>(ii)</b> <math>[5, 1, 1] \cdot k[-1, 0, 2] = -3k</math>  <math>\mathbf{r} \cdot [-1, 0, 2] = -3</math></p>	<p>M1 A1√ <b>2</b></p>	<p>For using same <math>\mathbf{n}</math> and substituting a point of <math>l_2</math>                  For obtaining correct <math>p</math>. <b>AEF</b> in this form                  f.t. on incorrect <math>\mathbf{n}</math></p>
<p><b>(iii)</b> <math>d = \frac{ -5+3 }{\sqrt{5}}</math> OR <math>d = \frac{ [2, -3, 2] \cdot [-1, 0, 2] }{\sqrt{5}}</math>                  OR <math>d</math> from <math>(5, 1, 1)</math> to <math>\Pi_1 = \frac{ 5(-1)+1(0)+1(2)+5 }{\sqrt{5}}</math>                  OR <math>d</math> from <math>(3, 4, -1)</math> to <math>\Pi_2 = \frac{ 3(-1)+4(0)-1(2)+3 }{\sqrt{5}}</math>                  OR <math>[3-t, 4, -1+2t] \cdot [-1, 0, 2] = -3 \Rightarrow t = \frac{2}{5}</math>                  OR <math>[5-t, 1, 1+2t] \cdot [-1, 0, 2] = -5 \Rightarrow t = -\frac{2}{5}</math>  <math>d = \frac{2}{\sqrt{5}} = \frac{2\sqrt{5}}{5} = 0.894427\dots</math></p>	<p>M1           A1√ <b>2</b></p>	<p>For using a distance formula from their equations                  Allow omission of <math>   </math>                      OR For finding intersection of <math>\mathbf{n}_1</math> and <math>\Pi_2</math> or <math>\mathbf{n}_2</math> and <math>\Pi_1</math>                    For correct distance <b>AEF</b>                  f.t. on incorrect <math>\mathbf{n}</math></p>
<p><b>(iv)</b> <math>d</math> is the shortest OR perpendicular distance between <math>l_1</math> and <math>l_2</math></p>	<p>B1 <b>1</b>  <b>10</b></p>	<p>For correct statement</p>
<p><b>7 (i)</b> <math>(z - e^{i\phi})(z - e^{-i\phi}) \equiv z^2 - (2)z \frac{(e^{i\phi} + e^{-i\phi})}{(2)} + 1</math>  <math>\equiv z^2 - (2 \cos \phi)z + 1</math></p>	<p>B1 <b>1</b></p>	<p>For correct justification <b>AG</b></p>
<p><b>(ii)</b> <math>z = e^{\frac{2k\pi i}{7}}</math>                  for <math>k = 0, 1, 2, 3, 4, 5, 6</math> OR <math>0, \pm 1, \pm 2, \pm 3</math></p> 	<p>B1 B1     B1 B1 <b>4</b></p>	<p>For general form OR any one non-real root                  For other roots specified                  (<math>k=0</math> may be seen in any form, eg <math>1, e^0, e^{2\pi i}</math>)                  For answers in form <math>\cos \theta + i \sin \theta</math> allow maximum                  B1 B0                   For any 7 points equally spaced round unit circle                  (circumference need not be shown)                  For 1 point on +ve real axis,                  and other points in correct quadrants</p>
<p><b>(iii)</b> <math>(z^7 - 1) = (z - 1)(z - e^{\frac{2\pi i}{7}})(z - e^{\frac{4\pi i}{7}})</math>  <math>(z - e^{\frac{6\pi i}{7}})(z - e^{\frac{-2\pi i}{7}})(z - e^{\frac{-4\pi i}{7}})(z - e^{\frac{-6\pi i}{7}})</math>  <math>= (z - e^{\frac{2\pi i}{7}})(z - e^{\frac{-2\pi i}{7}}) \times (z - e^{\frac{4\pi i}{7}})(z - e^{\frac{-4\pi i}{7}})</math>  <math>(z - e^{\frac{6\pi i}{7}})(z - e^{\frac{-6\pi i}{7}}) \times</math>  <math>\times (z - 1)</math>  <math>= (z^2 - (2 \cos \frac{2}{7}\pi)z + 1) \times</math>  <math>(z^2 - (2 \cos \frac{4}{7}\pi)z + 1) \times (z^2 - (2 \cos \frac{6}{7}\pi)z + 1) \times</math>  <math>\times (z - 1)</math></p>	<p>M1           M1 B1 A1 A1 <b>5</b>  <b>10</b></p>	<p>For using linear factors from (ii), seen or implied                            For identifying at least one pair of complex conjugate factors                  For linear factor seen                  For any one quadratic factor seen                  For the other 2 quadratic factors and expression written as product of 4 factors</p>

<p><b>8 (i)</b> Integrating factor <math>e^{\int \tan x \, dx}</math>  <math>= e^{-\ln \cos x}</math>  <math>= (\cos x)^{-1}</math> OR <math>\sec x</math>  <math>\Rightarrow \frac{d}{dx}(y(\cos x)^{-1}) = \cos^2 x</math>  <math>y(\cos x)^{-1} = \int \frac{1}{2}(1 + \cos 2x) \, dx</math>  <math>y(\cos x)^{-1} = \frac{1}{2}x + \frac{1}{4}\sin 2x + c</math>  <math>y = \left(\frac{1}{2}x + \frac{1}{4}\sin 2x + c\right)\cos x</math></p>	<p>B1 M1 A1 B1√ M1 M1 A1 A1 <b>8</b></p>	<p>For correct IF For integrating to ln form For correct simplified IF <b>AEF</b> For <math>\frac{d}{dx}(y \cdot \text{their IF}) = \cos^2 x \cdot \text{their IF}</math> For integrating LHS For attempting to use <math>\cos 2x</math> formula OR parts for <math>\int \cos^2 x \, dx</math> For correct integration both sides <b>AEF</b> For correct general solution <b>AEF</b></p>
<p><b>(ii)</b> <math>2 = \left(\frac{1}{2}\pi + c\right) \cdot -1 \Rightarrow c = -2 - \frac{1}{2}\pi</math>  <math>y = \left(\frac{1}{2}x + \frac{1}{4}\sin 2x - 2 - \frac{1}{2}\pi\right)\cos x</math></p>	<p>M1 A1 <b>2</b> <b>10</b></p>	<p>For substituting <math>(\pi, 2)</math> into their GS and solve for <math>c</math> For correct solution <b>AEF</b></p>
<p><b>9 (i)</b> <math>3^n \times 3^m = 3^{n+m}</math>, <math>n + m \in \mathbb{Z}</math>  <math>(3^p \times 3^q) \times 3^r = (3^{p+q}) \times 3^r = 3^{p+q+r}</math>  <math>= 3^p \times (3^{q+r}) = 3^p \times (3^q \times 3^r) \Rightarrow</math> associativity  Identity is <math>3^0</math>  Inverse is <math>3^{-n}</math>  <math>3^n \times 3^m = 3^{n+m} = 3^{m+n} = 3^m \times 3^n \Rightarrow</math> commutativity</p>	<p>B1 M1 A1 B1 B1 B1 <b>6</b></p>	<p>For showing closure For considering 3 distinct elements, seen bracketed 2+1 or 1+2 For correct justification of associativity For stating identity. Allow 1 For stating inverse For showing commutativity</p>
<p><b>(ii) (a)</b> <math>3^{2n} \times 3^{2m} = 3^{2n+2m} (= 3^{2(n+m)})</math>  Identity, inverse OK</p>	<p>B1* B1 (*dep) <b>2</b></p>	<p>For showing closure For stating other two properties satisfied and hence a subgroup</p>
<p><b>(b)</b> For <math>3^{-n}</math>,  <math>-n \notin</math> subset</p>	<p>M1 A1 <b>2</b></p>	<p>For considering inverse For justification of not being a subgroup <math>3^{-n}</math> must be seen here or in (i)</p>
<p><b>(c) EITHER:</b> eg <math>3^{1^2} \times 3^{2^2} = 3^5</math>  <math>\neq 3^{r^2} \Rightarrow</math> not a subgroup  OR: <math>3^{n^2} \times 3^{m^2} = 3^{n^2+m^2}</math>  <math>\neq 3^{r^2}</math> eg <math>1^2 + 2^2 = 5 \Rightarrow</math> not a subgroup</p>	<p>M1 A1 <b>2</b> M1 A1 <b>12</b></p>	<p>For attempting to find a specific counter-example of closure For a correct counter-example and statement that it is not a subgroup For considering closure in general For explaining why <math>n^2 + m^2 \neq r^2</math> in general and statement that it is not a subgroup</p>

**4727**

**Mark Scheme**

**June 2007**